

# PCEC Hydraulic Elevator Softstarters up to 150 HP @ 480 VAC

Unique advantages not found in electromechanical or other solid state starters



The PCE Hydraulic Elevator Softstarter and PCEC Panel Solution by Sprecher+Schuh are designed to simplify installation, set-up, and typical operation of motors that drive hydraulic elevators and escalators. This solid state starter solution is designed to operate 3 phase standard squirrel cage induction motors and can be connected to a 6 or 12 lead Wye-Delta (Star-Delta) or standard 3 or 9 lead motors. Through the use of LINE or INSIDE-THE-DELTA control, the solid state solution can provide ultimate control of the motor. The advantages of a solid state solution include the following:

### Provides smooth motor starting

- Decreases current surges on weak electrical systems
- Reduced starting torque of the motor helps to reduce mechanical stress on system components
- Helps meet both local and regional electrical codes when reduced voltage starting is a requirement
- Eliminates voltage and current spikes associated with traditional Wye-Delta (Star-Delta) starters
- Maximizes motor life due to reduced electrical strain
- Lowers general system maintenance requirements for improved uptime

The PCEC panel solution provides a standard PCE controller and a factory coordinated fault contactor on a common mounting plate for ease of installation. The PCE controller utilizes software optimized for the elevator industry along with a built-in selectable Class 10, 15 and 20 overload relay and SCR bypass to control all three phases. The pre-wired control harness (3 ft / ~1m flying leads) is supplied to simplify wiring into current installations while the mounting plate holes are the same as many standard Wye-Delta electro-mechanical starter panels. To insure start up performance both the PCE controller and PCEC panel assembly are factory tested before shipping.

The result is a quick and easy starter solution for the elevator and escalator industries.



### Microprocessor control provides precision operation

PCEC softstarters are under full microprocessor control, which limits starting current to the preset adjustable value. Current never exceeds the preset limit. Microprocessor control also provides finer increments of adjustment, facilitating smooth, repeatable, and accurate starting characteristics, independent of component aging and varying environmental conditions.

### LED diagnostic display

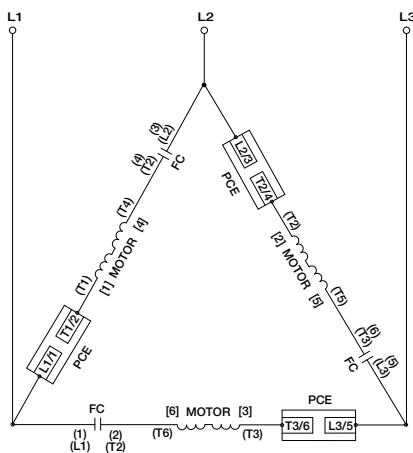
An LED display indicates operating status and fault condition (overload, over temperature, phase reversal/ phase loss, phase imbalance, shorted SCR, start fault). This enables speedy diagnosis and quick resolution of problems.

### Standard fault contactor

The PCEC panel solution is equipped with a standard fault contactor which isolates one side of the motor windings from the line power in case of softstarter fault or motor overload. Current flow is prevented by this mechanical isolation in addition to the solid state SCRs.

### UL/CSA Elevator Ratings

The PCEC Softstarters are UL Listed and cUL Listed (Canadian Standards per UL 508 and CS C22.2 No. 14-95) as solid state motor controllers in File E96956. They are also UL Listed and cUL Listed per UL 508 and CAN/CSA B44.1-96 as elevator controllers in File E3125.



PCEC Hydraulic Elevator Softstarters are wired "inside the delta" for more efficient operation and retrofit

**Modes of Operation (Standard)**

**Current Limit Starting**

Through the use of internal current sensors, the PCEC will regulate the current level applied to the motor over the programmed period of time. This type of motor control produces a slow start and insures that the current does not exceed the programmed level. This is standard configuration of the device and aligns well with traditional applications.

**Soft Start**

During Soft start, the voltage is ramped from an initial set point to full voltage over the programmed period of time. This type of motor control produces a smooth start in less time than the current limit setting, however the current is not restricted.

**Soft Stop**

Soft stop provides the ability to ramp down the voltage applied to the motor over a programmed period of time. The result is a smooth stop.

**Diagnostics**

Overload	The built in motor overload provides protection of the motor for over current conditions. This protection feature offers a user selectable setting called the trip class, which can be used to accommodate different applications and motor types. When the motor draws more than the nominal value of current for a period of time, the device will fault on a motor overload fault.
Over Temperature	The product includes a built in self monitoring method for detecting a SCR over-temperature condition. If the internal temperature exceeds a design threshold the device will fault on a SCR Overtemp fault.
Phase Reversal	The user can select the phase relationship of the incoming power. If this phase relationship changes, the device will fault indicating a problem.
Phase Loss/Open Load	When any one of the incoming 3 phases are lost, the controller will fault indicating a phase loss condition has occurred.
Phase Imbalance	When enabled, this motor protection feature will detect if a phase imbalance condition exists and fault the unit. A phase imbalance is defined as a 65% differential between the highest and lowest phase for more than 3 seconds.
Shorted SCR	Each time the PCEC initiates a start, it checks to see if the SCR's are operating correctly. If the controller is unable to properly turn on and off any one of the SCR's, the device will fault on a Shorted SCR fault.



### PCEC Controller Panel - 120V Control Voltage ④⑥

DELTA Connected - 6 Wire					Line Connected - 3 Wire ②					With 120VAC 50/60 Hz ③ Control Voltage  Catalog Number
Maximum Horsepower				Overload Range ①	Maximum Horsepower				Overload Range ①	
200V	240V	480V	575V		200V	240V	480V	575V		
10	10	20	30	10.9...32.9	5	5	10	15	6.3...19	PCEC-032-600V-120V
15	15	30	40	17...51	7.5	10	20	25	10...30	PCEC-051-600V-120V
20	20	40	60	21.3...64	10	10	25	30	12.3...37	PCEC-064-600V-120V
20	25	50	60	24.7...74	10	15	30	40	14.3...43	PCEC-074-600V-120V
30	40	75	100	34.7...104	15	20	40	50	20...60	PCEC-104-600V-120V
40	50	100	150	49...147	25	30	60	75	28.3...85	PCEC-147-600V-120V
75	75	150	200	59...234	40	50	100	125	34...135	PCEC-234-600V-120V ⑤

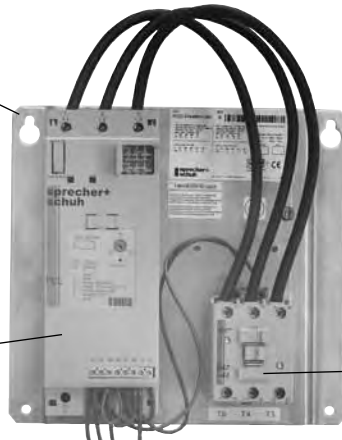
### PCEC Controller Panel - 230V Control Voltage ④⑥

DELTA Connected - 6 Wire					Line Connected - 3 Wire ②					With 230VAC 50/60 Hz ③ Control Voltage  Catalog Number
Maximum Horsepower				Overload Range ①	Maximum Horsepower				Overload Range ①	
200V	240V	480V	575V		200V	240V	480V	575V		
10	10	20	30	10.9...32.9	5	5	10	15	6.3...19	PCEC-032-600V-230V
15	15	30	40	17...51	7.5	10	20	25	10...30	PCEC-051-600V-230V
20	20	40	60	21.3...64	10	10	25	30	12.3...37	PCEC-064-600V-230V
20	25	50	60	24.7...74	10	15	30	40	14.3...43	PCEC-074-600V-230V
30	40	75	100	34.7...104	15	20	40	50	20...60	PCEC-104-600V-230V
40	50	100	150	49...147	25	30	60	75	28.3...85	PCEC-147-600V-230V
75	75	150	200	59...234	40	50	100	125	34...135	PCEC-234-600V-230V ⑤

- ① Motor FLA must fall within the specified range to operate correctly.
- ② The PCEC Controller panels are shipped in the DELTA connection mode by default. LINE connection requires the power wires to be reconfigured and DIP Switch #15 to be programmed for LINE connection mode by the customer.
- ③ Internal fan is optional for PCEC-032...064. See page D61 to purchase separately. All other PCEC units have internal fan as standard.
- ④ Purchase additional PCE Auxiliary Contact Blocks separately. See page D7. One Auxiliary Contact Block (one or two pole) may be mounted on the right side of the PCE controller.
- ⑤ Separate 120V or 240V single phase is required for PCEC fan operation.
- ⑥ The PCEC Hydraulic Elevator duty rating is 80 starts per hour at 50% duty cycle (160 calls per hour). Starts per hour are based on when the motor starts, the motor only runs on "up" calls.

PCEC Controller Panel  
(Complete Assembly)

PCE Controller Only



Fault Contactor

**Replacement Parts**

Complete Assembly (For Reference Only)	PCE Controller Only
PCEC-032-600V-120V	<b>PCE-032-600V</b>
PCEC-051-600V-120V	<b>PCE-051-600V</b>
PCEC-064-600V-120V	<b>PCE-064-600V</b>
PCEC-074-600V-120V	<b>PCE-074-600V</b>
PCEC-104-600V-120V	<b>PCE-104-600V</b>
PCEC-147-600V-120V	<b>PCE-147-600V</b>
PCEC-234-600V-120V	<b>PCE-234-600V</b>

PCEC-032-600V-230V	<b>PCE-032-600V</b>
PCEC-051-600V-230V	<b>PCE-051-600V</b>
PCEC-064-600V-230V	<b>PCE-064-600V</b>
PCEC-074-600V-230V	<b>PCE-074-600V</b>
PCEC-104-600V-230V	<b>PCE-104-600V</b>
PCEC-147-600V-230V	<b>PCE-147-600V</b>
PCEC-234-600V-230V	<b>PCE-234-600V</b>

PCE Fans
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PCV-064  
(optional)

PCV-147

PCV-234

PCV-064  
(optional)

PCV-147

PCV-234

Fault Contactor
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CA7-37-00-120

CA7-37-00-120

CA7-37-00-120

CA7-43-00-120

CA7-60-00-120

CA7-85-00-120

CA6-180-EI-11-120

CA7-37-00-240

CA7-37-00-240

CA7-37-00-240

CA7-43-00-240

CA7-60-00-240

CA7-85-00-240

CA6-180-EI-11-220W

Fault Contactor Coil
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TC473

TD473

TE473

TE473

CA6-TGE865

TC858

TD858

TE858

TE858

CA6-TGE866

**Electrical**

<b>Power Circuit</b>	<b>UL/cUL/CSA</b>	<b>IEC</b>
Rated Operational Voltage	200...600V AC	200...500V~
Rated Insulation Voltage	600V AC	500V~
Dielectric Withstand	2200V AC	2500V~
Repetitive Peak	200...600V AC: 1600	500V~: 1600
Rated Impulse Voltage		6 kV
Over-voltage Category		III
Number of Poles	Equipment designed for 3 phase only	
Operating Frequency	50/60 Hz	
Controller Utilization Category	32/51/64	AC-53b: 3.5-15:3585
	74/104/147	AC-53b: 4.5-30:1770
	234	AC-53b: 3.5-30:1770
Overload Current Range (Amps)	LINE	DELTA
	32	10.9...32.8
	51	17...51
	64	21.3...64
	74	24.7...74
	104	34.7...104
	147	49 ...147
	234	59...234
<b>Control Circuit</b>		
	<b>UL/cUL/CSA</b>	<b>IEC</b>
Rated Operational Voltage	100...120 V AC, 200...240V AC	120~, 240~
Rated Insulation Voltage	NA	300V~
Dielectric Withstand	NA	3000V
Rated Impulse Voltage		3kV
Operating Frequency	50/60 Hz	
Control Power Requirements	32/51/64	215 mA @ 120 V AC , 180 mA @ 240 V AC
	74/104/147	200 mA @ 120 V AC , 100 mA @ 240 V AC
	234	200 mA @ 120 V AC , 120 mA @ 240 V AC
Fan Power Requirements	32/51/64	NA
	74/104/147	NA
	234	20 VA

**Electrical (continued)**

Short Circuit Performance		Type 1	
Device Current Rating	Max Fuse Size and Type	Max Available Fault Rating	
32	70 A - RK5	5 kA	
	125 A - K5	5 kA	
51	125 A - RK5	5 kA	
	200 A - K5	10 kA	
64	125 A - RK5	5 kA	
	200 A - K5	10 kA	
74	150 A - RK5	5 kA	
	250 A - J	10 kA	
104	200 A - RK5	5 kA	
	400 A - J	10 kA	
147	250 A - RK5	10 kA	
	400 A - J	10 kA	
234	400 A - RK5	10 kA	
	450 A - K5	10 kA	

Auxiliary Contacts (Fault and Aux#1)	UL/cUL/CSA	IEC
Rated Operational Voltage	250V AC / 30V DC	250V~ / 30V DC
Rated Insulation Voltage	250V	250V~
Rated Impulse Voltage	NA	4kV
Dielectric Withstand	1500V AC	2000V~
Operating Frequency	50/60 Hz	
Utilization Category	D300	AC-15 / DC
Type of Control Circuit	Electromagnetic Relay	
Number of Contacts	1	
Type of contacts	Normally Open (N.O.)	
Type of current	AC/DC	
Rated Operational Current (Max.)	0.6 A @ 120 V~ and 0.3 A @ 240V~	
Conventional Thermal Current (Ith)	1 Amp	
Make/Break VA	432/72	

**Mechanical**

Resistance to Vibration	Operational	1.0 G Peak, 0.15 mm (0.006 in) displacement
	Non-operational	2.5 G Peak, 0.38 mm (0.015 in) displacement
Resistance to Shock	Operational	15 G
	Non-operational	5.5 G

**Environmental**

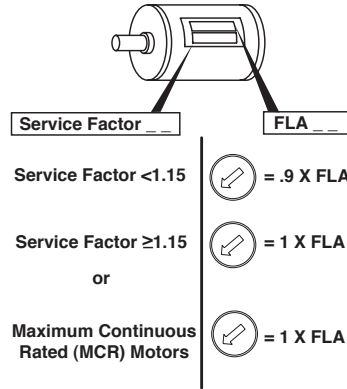
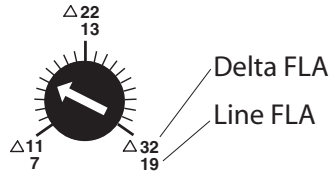
Operating Temperature	0...50°C (32...122°F) Open
	0...40°C (32...104°F) Enclosed
Altitude	2000 m (6560 ft)
Humidity	5...95% (non-condensing)
Pollution Degree	2

**UL/CSA Elevator Ratings**

The PCEC Softstarters are UL Listed and cUL Listed (Canadian Standards per UL 508 and CS C22.2 No. 14-95) as solid state motor controllers in File E96956. They are also UL Listed and cUL Listed per UL 508 and CAN/CSA B44.1-96 as elevator controllers in File E3125.

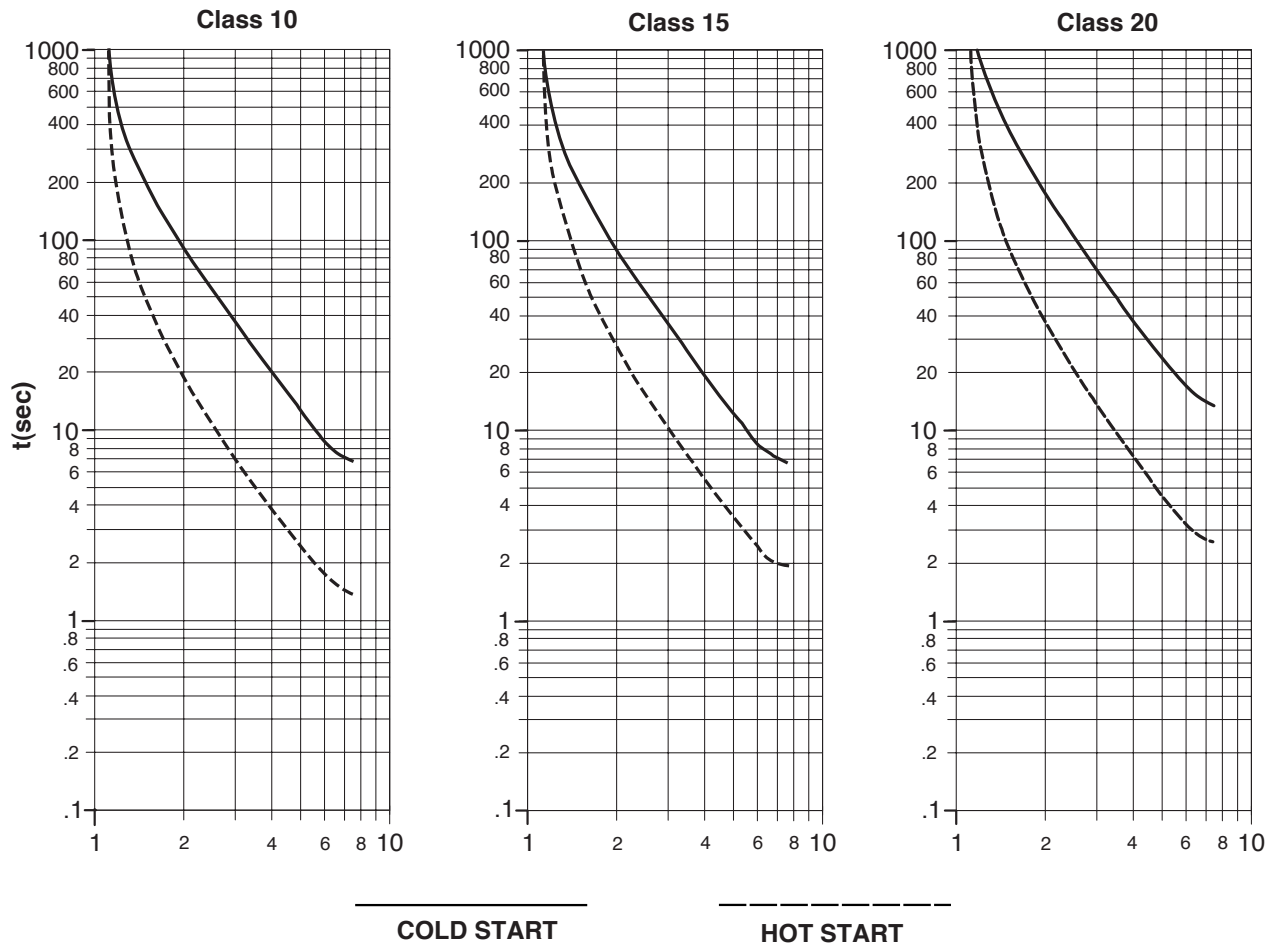
### Motor FLA Adjustments

The front of the PCE controller contains a dial which is used for setting the actual FLA of the motor. The label is designed to accommodate motors connected in the LINE or DELTA mode. To determine the proper setting, look at the motors nameplate and set the dial accordingly. The dial setting can be modified depending on the service factor of the motor as shown:



### Motor Overload Trip Curves

The trip class should be set according to the motors maximum permissible locked rotor time or the general thermal capabilities. Consult the motor manufacturer for recommendations on setting the trip class.



**Terminal Torque Specifications**
**PCE Controller Information**

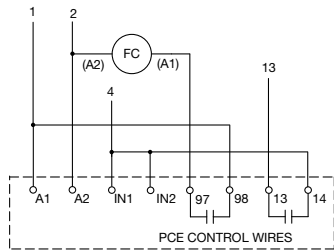
Controller Size	Units	Line Power Terminals	Load Power Terminals	Control Power Terminals
32/51/64	Wire Size	14 - 4 AWG (2.5 - 25 mm <sup>2</sup> )	14 - 6 AWG (2.5 - 16 mm <sup>2</sup> )	24 - 14 AWG (0.2 - 2.5 mm <sup>2</sup> )
	Torque	20 - 25 lb-in. (2.3 - 2.8 Nm)	20 - 22.5 lb-in. (2.3 - 2.6 Nm)	4.4 - 8 lb-in. (0.5 - 0.9 Nm)
74/104/147	Wire Size	14 - 3/0 AWG (2.5 - 95 mm <sup>2</sup> )	14 - 1 AWG (2.5 - 50 mm <sup>2</sup> )	24 - 14 AWG (0.2 - 2.5 mm <sup>2</sup> )
	Torque	100 - 110 lb-in. (11.3 - 12.4 Nm)	100 - 110 lb-in. (11.3 - 12.4 Nm)	4.4 - 8 lb-in. (0.5 - 0.9 Nm)
234	Wire Size	6 - 250 AWG (16 - 120 mm <sup>2</sup> )	6 - 250 AWG (16 - 120 mm <sup>2</sup> )	24 - 14 AWG (0.2 - 2.5 mm <sup>2</sup> )
	Torque	275 lb-in. (31 Nm)	275 lb-in. (31 Nm)	4.4 - 8 lb-in. (0.5 - 0.9 Nm)

**Fault Contactor Information**

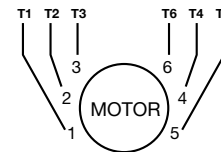
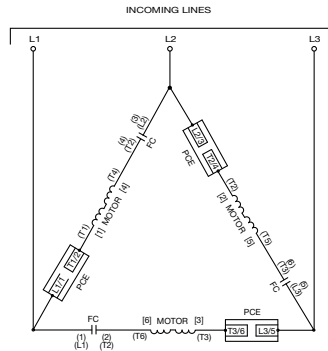
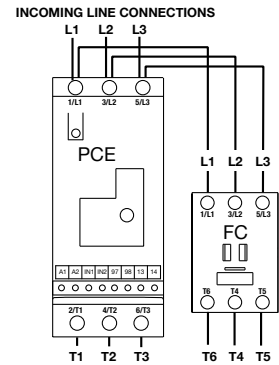
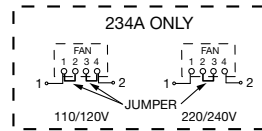
Controller Size	Units	Line Power Terminals	Load Power Terminals	Control Power Terminals
32/51/64/74	Wire Size	14 - 4 AWG (2.5 - 16 mm <sup>2</sup> )	14 - 4 AWG (2.5 - 16 mm <sup>2</sup> )	16 - 12 AWG (1.5 - 6 mm <sup>2</sup> )
	Torque	22 - 35 lb. in. (2.5 - 4 Nm)	22 - 35 lb. in. (2.5 - 4 Nm)	9 - 13 lb. in. (1 - 2.5 Nm)
104/147	Wire Size	14 - 1 AWG (2.5 - 35 mm <sup>2</sup> )	14 - 1 AWG (2.5 - 35 mm <sup>2</sup> )	16 - 12 AWG (1.5 - 6 mm <sup>2</sup> )
	Torque	31 - 53 lb. in. (3.5 - 6 Nm)	31 - 53 lb. in. (3.5 - 6 Nm)	9 - 13 lb. in. (1 - 2.5 Nm)
234	Wire Size	6 - 300 AWG (16 - 150 mm <sup>2</sup> )	6 - 300 AWG (16 - 150 mm <sup>2</sup> )	2x 16...12 AWG (2x 1...4 mm <sup>2</sup> )
	Torque	250 lb-in. (28 Nm)	250 lb-in. (28 Nm)	12 - 20 lb-in. (1.4 - 2.3 Nm)



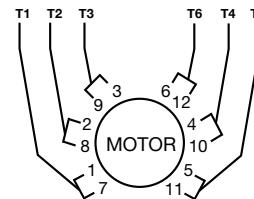
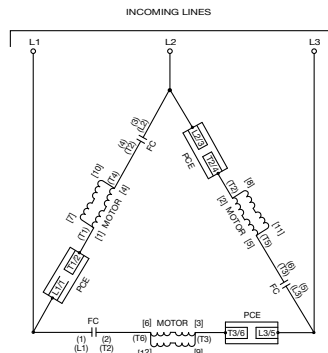
**DELTA Connection Diagrams, Power, and Motor Wiring**



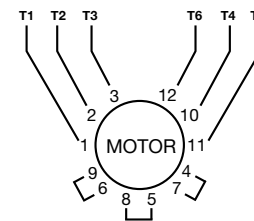
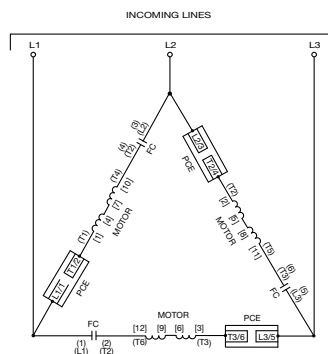
- 1- CONTROL POWER (L)
- 2- CONTROL COMMON (N)
- 4- START ENABLE
- 13- UP TO SPEED INDICATION



6 LEAD MOTOR CONNECTIONS							
STARTER TERMINALS	T1	T2	T3	T6	T4	T5	JUMPER
MOTOR TERMINALS	1&7	2&8	3&9	6&12	4&10	5&11	N/A



12 LEAD 230V LOW VOLTAGE MOTOR CONNECTIONS							
STARTER TERMINALS	T1	T2	T3	T6	T4	T5	JUMPER
MOTOR TERMINALS	1&7	2&8	3&9	6&12	4&10	5&11	N/A

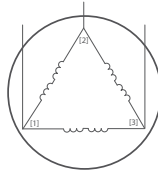
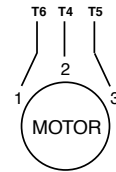
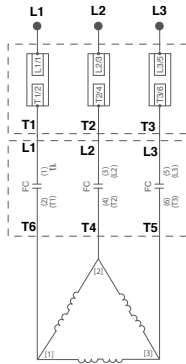
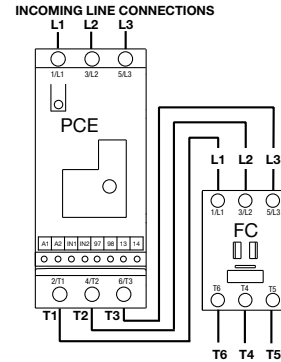
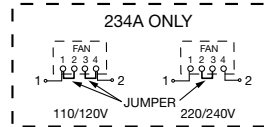
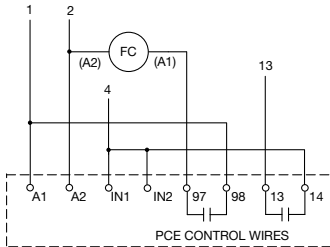


12 LEAD 460V HIGH VOLTAGE MOTOR CONNECTIONS							
STARTER TERMINALS	T1	T2	T3	T6	T4	T5	JUMPER
MOTOR TERMINALS	1	2	3	12	10	11	4&7 5&8 6&9

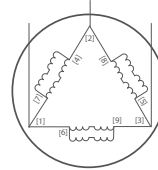
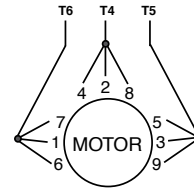
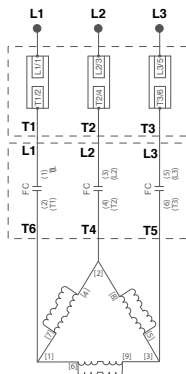
**LINE Connection Diagrams, Power, and Motor Wiring**

Note: The power wire configuration and dip switch settings must be changed for the line connection method

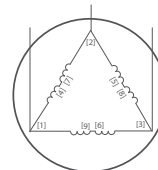
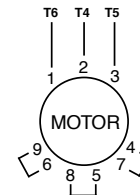
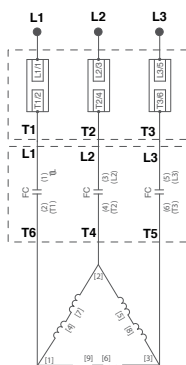
- 1- CONTROL POWER (L)
- 2- CONTROL COMMON (N)
- 4- START ENABLE
- 13- UP TO SPEED INDICATION



3 LEAD MOTOR CONNECTIONS				
STARTER TERMINALS	T6	T4	T5	JUMPER
MOTOR TERMINALS	1	2	3	N/A



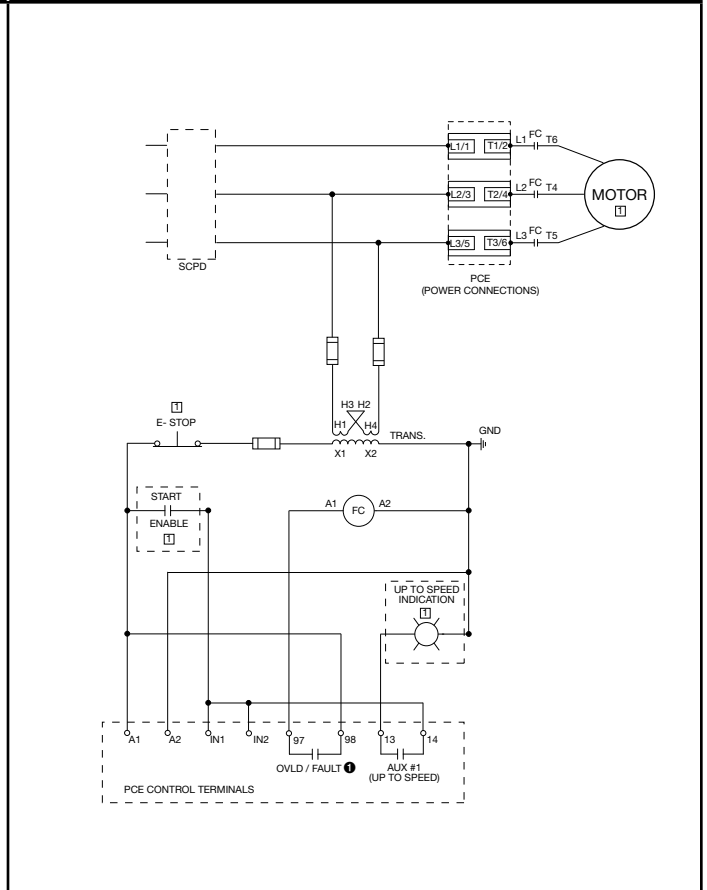
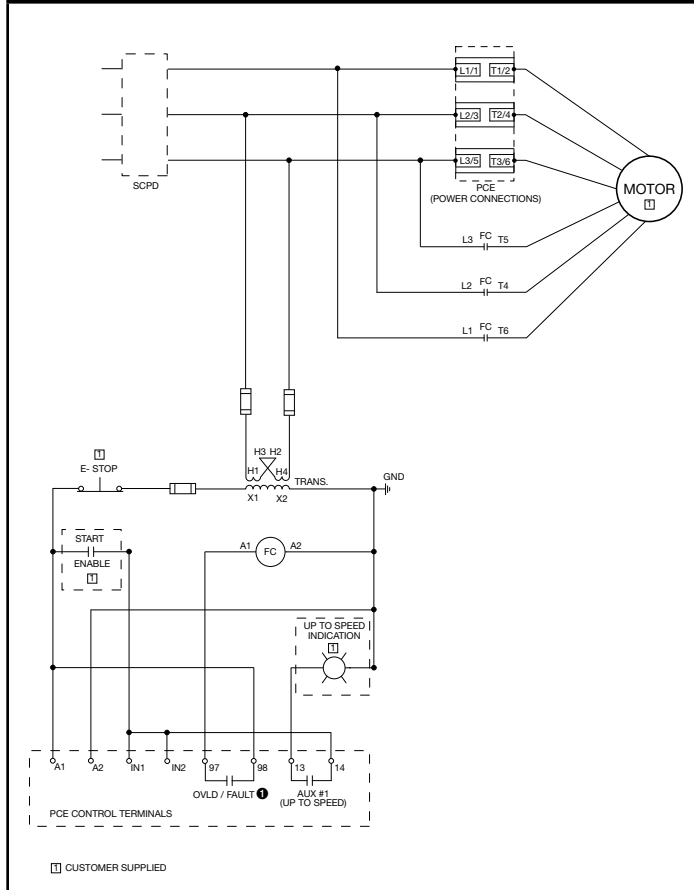
9 LEAD 230V LOW VOLTAGE MOTOR CONNECTIONS				
STARTER TERMINALS	T6	T4	T5	JUMPER
MOTOR TERMINALS	1,6,7	2,4,8	3,5,9	N/A



9 LEAD 460V HIGH VOLTAGE MOTOR CONNECTIONS				
STARTER TERMINALS	T6	T4	T5	JUMPER
MOTOR TERMINALS	1	2	3	4&7 5&8 6&9

**DELTA Connected Controller - Typical Control Wiring**

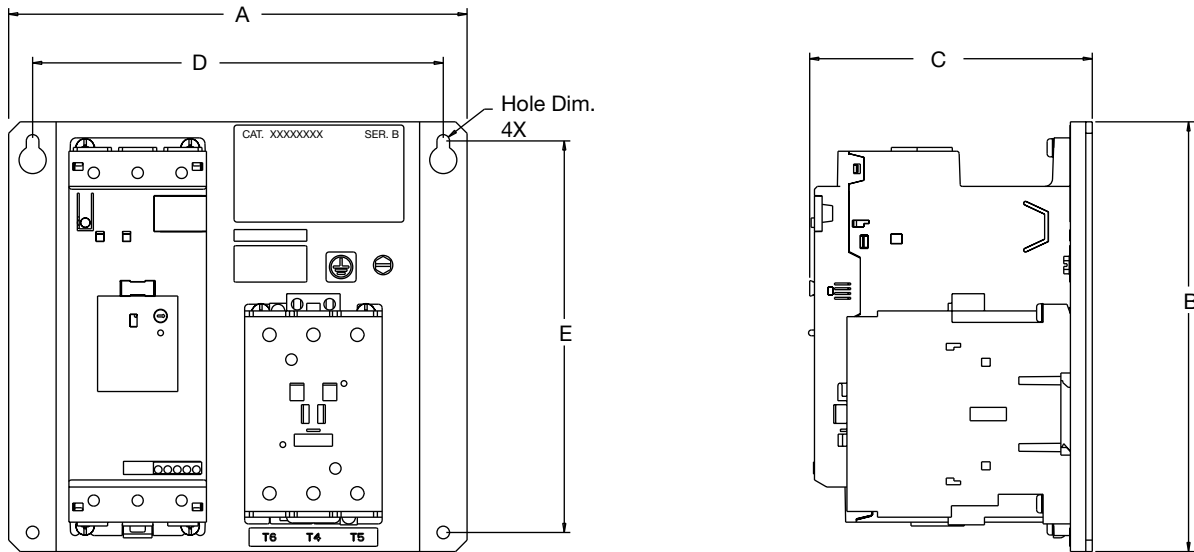
**LINE Connected Controller - Typical Control Wiring**



1 When (A1)(A2) control power is applied, (97)(98) contact closes instantaneously and opens when the PCE detects an overload or fault condition, or when control power is removed.

**PCEC Hydraulic Elevator Softstarter**

Dimensions are in millimeters (inches). Dimensions not intended for manufacturing purposes.



Controller Size	Units	A (Width)	B (Height)	C (Depth)	D	E	Hole Dim - 4x	Approx. Weight
32/51/64	mm	178	144	115.7	165.1	127.0	5.6	4 lbs (2 kg)
	in	7.01	5.67	4.56	6.50	5.00	0.22	
74/104/147	mm	240	225	147.9	215	205	6.6	14 lbs (6 kg)
	in	9.45	8.86	5.82	8.46	8.07	0.260	
234	mm	362	515	216.4	330.2	489.5	8.7	51 lbs (23 kg)
	in	14.25	20.28	8.52	13.00	19.27	0.343	